

Parametric estimation through
divergences. Duality
approach: good and bad points

M. Broniatowski, LSTA, Université Paris 6. Joint work
and reflections with colleagues in Paris,
Bucarest and in Prague

October 14, 2009

For any signed finite measure Q in $\mathcal{M}(P)$, the ϕ -divergence between Q and P is defined by

$$D_\phi(Q, P) := \int_{\mathcal{X}} \phi \left(\frac{dQ}{dP}(x) \right) dP(x). \quad (1)$$

When Q is not a.c. w.r.t. P , we set $D_\phi(Q, P) = +\infty$. The ϕ -divergences were introduced by I. Csiszar as “ f -divergences”. For all p.m. P , the mappings $Q \in \mathcal{M} \mapsto D_\phi(Q, P)$ are convex and take nonnegative values. When $Q = P$ then $D_\phi(Q, P) = 0$. Furthermore, if the function $x \mapsto \phi(x)$ is strictly convex on a neighborhood of $x = 1$, then the following fundamental property holds

$$D_\phi(Q, P) = 0 \text{ if and only if } Q = P. \quad (2)$$

All these properties are presented in Csiszar (1967), Liese and Vajda (1987) for ϕ -divergences defined on the set of all p.m.’s \mathcal{M}^1 . When the ϕ -divergences are defined on \mathcal{M} , then the same properties hold. In general $D_\phi(Q, P)$ and $D_\phi(P, Q)$ are not equal. Hence, ϕ -divergences usually are not distances, but they merely measure some difference between two measures. A main feature of divergences between distributions of random variables X and

\mathcal{Y} is the invariance property with respect to common smooth change of variables.

0.1 Examples of ϕ -divergences.

When defined on \mathcal{M}^1 , the Kullback-Leibler (KL),

$$\phi(x) = x \log x - x + 1,$$

modified Kullback-Leibler (KL_m)

$$\phi(x) = -\log x + x - 1$$

, χ^2

$$\phi(x) = \frac{1}{2}(x - 1)^2$$

, modified χ^2 (χ_m^2)

$$\phi(x) = \frac{1}{2}(x - 1)^2/x$$

, Hellinger (H)

$$\phi(x) = 2(\sqrt{x} - 1)^2$$

, and L_1

$$\phi(x) = |x - 1|$$

power divergences" (Rényi, Cressie Read). They are defined through the class of convex functions

$$x \in]0, +\infty[\mapsto \phi_\gamma(x) := \frac{x^\gamma - \gamma x + \gamma - 1}{\gamma(\gamma - 1)} \quad (3)$$

The χ^2 -divergence: the corresponding ϕ function $\phi_2(x) := \frac{1}{2}(x - 1)^2$ is defined and convex on whole \mathbb{R} .

Estimation and test using ϕ -divergences. An i.i.d. sample X_1, \dots, X_n with common unknown distribution

P is observed and some p.m. Q is given. We aim to estimate $D_\phi(Q, P)$ and, more generally, $\inf_{Q \in \Omega} D_\phi(Q, P)$ where Ω is some set of measures, as well as the measure Q^* achieving the infimum on Ω . In the parametric context, these problems can be well defined and lead to new results in estimation and tests, extending classical notions.

0.1.1 Parametric estimation and tests

Let $\{P_\theta; \theta \in \Theta\}$ be some parametric model with Θ an open set in \mathbb{R}^d . On the basis of an i.i.d. sample X_1, \dots, X_n with distribution P_{θ_T} , we want to estimate θ_T , the unknown true value of the parameter and perform statistical tests on the parameter using ϕ -divergences. When all p.m.'s P_θ share the same finite support S ,

$$\tilde{\theta}_\phi := \arg \inf_{\theta \in \Theta} D_\phi(P_\theta, P_n). \quad (4)$$

Various parametric tests can be performed based on the previous estimates of ϕ -divergences; Lindsay 1994, Morales

Pardo Vajda 1995nd The class of estimates (4) contains the maximum likelihood estimate (MLE). Indeed, when $\phi(x) = \phi_0(x) = -\log x + x - 1$, we obtain

$$\tilde{\theta}_{KL_m} := \arg \inf_{\theta \in \Theta} KL_m(P_\theta, P_n) = \arg \inf_{\theta \in \Theta} \sum_{j \in S} -\log(P_\theta(j)) P_n(j)$$

Robustness and divergences? Lindsay 199, Basu-Lindsay 1994 Jimenez Shao (2001)

When the support S is continuous, the plug-in estimates are not well defined;

Smoothing (kernel) .example: Hellinger distance: Beran (1977). However: does not include MLE.

1 Dual representation for ϕ -divergences

Liese and Vajda 2006, Broniatowski and Kéziou 2006, on different proofs. Here the French approach

. The Fenchel-Legendre transform of ϕ will be denoted ϕ^* , i.e.,

$$t \in \mathbb{R} \mapsto \phi^*(t) := \sup_{x \in \mathbb{R}} \{tx - \phi(x)\},$$

By the closedness of ϕ , applying the duality principle, the conjugate ϕ^{**} of ϕ^* coincides with ϕ , i.e.,

$$\phi^{**}(t) := \sup_{x \in \mathbb{R}} \{tx - \phi^*(x)\} = \phi(t), \quad \text{for all } t \in \mathbb{R}.$$

If additionally ϕ is strictly convex, then for all $t \in \text{Im}\phi'$ we have

$$\phi^*(t) = t\phi'^{-1}(t) - \phi(\phi'^{-1}(t)) \quad \text{and} \quad \phi^{*\prime}(t) = \phi'^{-1}(t).$$

.

Let \mathcal{F} be some class of \mathcal{B} -measurable real valued functions f defined on \mathcal{X} , and denote $\mathcal{M}_{\mathcal{F}}$, the real vector subspace of \mathcal{M} , defined by

$$\mathcal{M}_{\mathcal{F}} := \left\{ Q \in \mathcal{M} \text{ such that } \int |f| d|Q| < \infty, \text{ for all } f \in \mathcal{F} \right\}.$$

Theorem 1 *Assume that ϕ is differentiable. Then, for all $Q \in \mathcal{M}_{\mathcal{F}}$ such that $D_{\phi}(Q, P)$ is finite and $\phi' \left(\frac{dQ}{dP} \right)$ belongs to \mathcal{F} , the ϕ -divergence $D_{\phi}(Q, P)$ admits the dual representation*

$$D_{\phi}(Q, P) = \sup_{f \in \mathcal{F}} \left\{ \int f \, dQ - \int \phi^*(f) \, dP \right\}, \quad (5)$$

and the function $f := \phi' \left(\frac{dQ}{dP} \right)$ is an optimal solution. Furthermore, if ϕ is essentially smooth then $f := \phi' \left(\frac{dQ}{dP} \right)$ is the unique optimal solution (P -a.e.).

Any class F containing $f := \phi' \left(\frac{dQ}{dP} \right)$ and such that $\int |f| \, d|Q| < \infty$, for all $f \in F$ holds can be used.

2 Parametric estimation and tests through minimum ϕ -divergence approach

For a given **escort parameter** $\theta \in \Theta$, consider the class of functions **(the smallest when θ_T is unknown and under the model)**

$$\mathcal{F} = \mathcal{F}_\theta := \left\{ x \mapsto \phi' \left(\frac{p_\theta(x)}{p_\alpha(x)} \right); \alpha \in \Theta \right\}.$$

Then

$$D_\phi(\theta, \theta_T) = \sup_{f \in \mathcal{F}_\theta} \left\{ \int f dP_\theta - \int \phi^*(f) dP_{\theta_T} \right\},$$

which, by (??), can be written as

$$D_\phi(\theta, \theta_T) = \sup_{\alpha \in \Theta} \left\{ \int \phi' \left(\frac{p_\theta}{p_\alpha} \right) dP_\theta - \int \left[\frac{p_\theta}{p_\alpha} \phi' \left(\frac{p_\theta}{p_\alpha} \right) - \phi \left(\frac{p_\theta}{p_\alpha} \right) \right] dP_{\theta_T} \right\}. \quad (6)$$

The supremum in this display is unique and it is achieved at $\alpha = \theta_T$ independently upon the value of θ . Hence, it is reasonable to estimate $D_\phi(\theta, \theta_T) := \int \phi(p_\theta/p_{\theta_T}) dP_{\theta_T}$, the ϕ -divergence between P_θ and P_{θ_T} , by

$$\widehat{D}_\phi(\theta, \theta_T) := \sup_{\alpha \in \Theta} \left\{ \begin{array}{l} \int \phi' \left(\frac{p_\theta}{p_\alpha} \right) dP_\theta \\ - \int \left[\frac{p_\theta}{p_\alpha} \phi' \left(\frac{p_\theta}{p_\alpha} \right) - \phi \left(\frac{p_\theta}{p_\alpha} \right) \right] dP_n \end{array} \right\}, \quad (7)$$

in which we have replaced P_{θ_T} by its estimate P_n , the empirical measure associated to the data.

Since the supremum in (6) is unique and it is achieved at $\alpha = \theta_T$, define the following class of

M-estimates of θ_T

$$\widehat{\alpha}_\phi(\theta) := \arg \sup_{\alpha \in \Theta} \left\{ \begin{array}{l} \int \phi' \left(\frac{p_\theta}{p_\alpha} \right) dP_\theta \\ - \int \left[\frac{p_\theta}{p_\alpha} \phi' \left(\frac{p_\theta}{p_\alpha} \right) - \phi \left(\frac{p_\theta}{p_\alpha} \right) \right] dP_n \end{array} \right\} \quad (8)$$

. Further, we have **(natural estimator deduced from the previous one, minimize on the escort)**

$$\inf_{\theta \in \Theta} D_{\phi}(\theta, \theta_T) = D_{\phi}(\theta_T, \theta_T) = 0.$$

The infimum in this display is unique and it is achieved at $\theta = \theta_T$. It follows that a natural definition of a second estimate is

$$\hat{\theta}_{\phi} := \arg \inf_{\theta \in \Theta} \sup_{\alpha \in \Theta} \left\{ \begin{array}{l} \int \phi' \left(\frac{p_{\theta}}{p_{\alpha}} \right) dP_{\theta} \\ - \int \left[\frac{p_{\theta}}{p_{\alpha}} \phi' \left(\frac{p_{\theta}}{p_{\alpha}} \right) - \phi \left(\frac{p_{\theta}}{p_{\alpha}} \right) \right] dP_n \end{array} \right\}. \quad (9)$$

3 Everything is OK under the model with any escort parameter, and solves old problems

Theorem 2 *Under standard conditions of integrability and domination (exchange \int and $\frac{d}{d\theta}$)*

(a) Let $B(\theta_T, n^{-1/3}) := \{\alpha \in \Theta; \|\alpha - \theta_T\| \leq n^{-1/3}\}$.
 Then, as $n \rightarrow \infty$, with probability one, the estimate $\hat{\alpha}_\phi(\theta)$ is $n^{1/3}$ -consistent and satisfies $P_n(\partial/\partial\alpha)h(\theta, \hat{\alpha}_\phi(\theta)) = 0$ (is a regular M-estimator).

(b) $\sqrt{n} (\hat{\alpha}_\phi(\theta) - \theta_T)$ converges in distribution to a centered multivariate normal random variable with covariance matrix

$$V_\phi(\theta, \theta_T) = S^{-1}MS^{-1} \quad (10)$$

with $S := -P_{\theta_T}(\partial^2/\partial\alpha^2)h(\theta, \theta_T)$ and $M := P_{\theta_T}(\partial/\partial\alpha)h(\theta, \theta_T)$.
 If $\theta_T = \theta$, then $V_\phi(\theta, \theta_T) = V(\theta_T) = I_{\theta_T}^{-1}$ with I_{θ_T} the Fisher Information matrix .

(c) If $\theta_T = \theta$, then the statistic $\frac{2n}{\phi''(1)}\widehat{D}_\phi(\theta, \theta_T)$ converges in distribution to a χ^2 random variable with d degrees of freedom.

(d) when $\theta \neq \theta_T$, we have
 $\sqrt{n} (\widehat{D}_\phi(\theta, \theta_T) - D_\phi(\theta, \theta_T))$ converges in distribution

to a centered normal random variable with variance

$$\sigma_{\phi}^2(\theta, \theta_T) = P_{\theta_T} h(\theta, \theta_T)^2 - \left(P_{\theta_T} h(\theta, \theta_T) \right)^2.$$

Remark 3 Using theorem ?? part (c), the estimate $\widehat{D}_{\phi}(\theta_0, \theta_T)$ can be used to perform statistical tests (asymptotically of level ϵ) of the null hypothesis $\mathcal{H}_0 : \theta_T = \theta_0$ against the alternative $\mathcal{H}_1 : \theta_T \neq \theta_0$ for a given value θ_0 . Since $D_{\phi}(\theta_0, \theta_T)$ is nonnegative and takes value zero only when $\theta_T = \theta_0$, the tests are defined through the critical region

$$C_{\phi}(\theta_0, \theta_T) := \left\{ \frac{2n}{\phi''(1)} \widehat{D}_{\phi}(\theta_0, \theta_T) > q_{d, \epsilon} \right\} \quad (11)$$

where $q_{d, \epsilon}$ is the $(1 - \epsilon)$ -quantile of the χ^2 distribution with d degrees of freedom. Note that these tests are all consistent, since $\widehat{D}_{\phi}(\theta_0, \theta_T)$ are n -consistent estimates of $D_{\phi}(\theta_0, \theta_T) = 0$ under \mathcal{H}_0 , and \sqrt{n} -consistent estimate of $D_{\phi}(\theta_0, \theta_T) > 0$ under \mathcal{H}_1 ; see part (c) and (d) in theorem ?? above. Further, the asymptotic result (d) in theorem ?? above can be used to give approximation of

the power function $\theta_T \mapsto \beta(\theta_T) := P_{\theta_T} (C_\phi(\theta_0, \theta_T))$.

We obtain then the following approximation

$$\beta(\theta_T) \approx 1 - F_{\mathcal{N}} \left(\frac{\sqrt{n}}{\sigma_\phi(\theta_0, \theta_T)} \left[\frac{\phi''(\mathbf{1})}{2n} q_{d,\epsilon} - D_\phi(\theta_0, \theta_T) \right] \right) \quad (12)$$

where $F_{\mathcal{N}}$ is the cumulative distribution function of a normal random variable with mean zero and variance one.

An important application of this approximation is the approximate sample size (13) below that ensures a power β for a given alternative $\theta_T \neq \theta_0$. Let n_0 be the positive root of the equation

$$\beta = 1 - F_{\mathcal{N}} \left(\frac{\sqrt{n}}{\sigma_\phi(\theta_0, \theta_T)} \left[\frac{\phi''(\mathbf{1})}{2n} q_{d,\epsilon} - D_\phi(\theta_0, \theta_T) \right] \right)$$

i.e., $n_0 = \frac{(a+b) - \sqrt{a(a+2b)}}{2D_\phi(\theta_0, \theta_T)^2}$ where $a = \sigma_\phi^2(\theta_0, \theta_T) [F_{\mathcal{N}}^{-1}(1 - \beta)]^2$

and $b = \phi''(\mathbf{1}) q_{d,\epsilon} D_\phi(\theta_0, \theta_T)$. The required sample size is then

$$n^* = [n_0] + 1 \quad (13)$$

where $[.]$ is used here to denote "integer part of".

3.1 A simple solution to the problem of testing the number of components in a mixture

Consider the following set of signed finite measures

$$p_\theta := (1 - \theta)p_0 + \theta p_1 \text{ where } \theta \in \mathbb{R}. \quad (14)$$

This set (of signed finite measures with mass one) obviously contains the mixture model (??). In particular, the null value of θ_T (i.e., $\theta_T = 0$) is an **interior point** of the parameter space \mathbb{R} . The likelihood ratio test (for a model of signed measures) cannot be used since the log-likelihood $l(\theta)$ may be infinite (when $\theta < 0$ or $\theta > 1$). In the context of divergences, this means that the estimate $\widehat{KL}_m(P_0, P_{\theta_T})$ may be infinite if we consider the model (14), which is due to the fact that the corresponding convex function $\phi(x) = -\log x + x - 1$ is infinite on \mathbb{R}_- . This suggests to use a divergence associated to a convex function ϕ which is finite on all \mathbb{R} , for instance, the

χ^2 -divergence (which is associated to the convex function $\phi(x) = \frac{1}{2}(x - 1)^2$). So, in order to perform a test asymptotically of level ϵ for (??), we propose to use the following estimate of the χ^2 -divergence between P_0 and P_{θ_T}

$$\widetilde{\chi^2}(0, \theta_T) = \sup_{\alpha \in \Theta_e} \{P_0 f(0, \alpha) - P_n g(0, \alpha)\}, \quad (15)$$

where $f(0, \alpha) = p_0/p_\alpha - 1$ and $g(0, \alpha) = 1/2(p_0/p_\alpha + 1)(p_0/p_\alpha - 1)$ as a consequence of definitions (??) and (??), and Θ_e is the new parameter space which we define as follows

$$\Theta_e := \left\{ \alpha \in R \text{ such that } \int |f(0, \alpha)| dP_0 \text{ is finite} \right\}.$$

The value of the parameter θ_T under the null hypothesis \mathcal{H}_0 , i.e., $\theta_T = 0$, is in the interior of the new parameter space Θ_e which is generally non void. Hence, under conditions of theorem ?? where Θ is replaced by Θ_e and θ by zero, under \mathcal{H}_0 the statistic $2n\widetilde{\chi^2}(0, \theta_T)$ converges in distribution to a χ^2 random variable with one degree of freedom; the critical region takes then the form

$$CR := \left\{ 2n\widetilde{\chi^2}(0, \theta_T) > q_{1,\epsilon} \right\},$$

where $q_{1,\epsilon}$ is the $(1 - \epsilon)$ -quantile of the χ^2 distribution with one degree of freedom. Obviously other divergences which are associated to convex functions finite on all \mathbb{R} can be used.

4 Semiparametrics

We consider a **nonlinear regression problem**, that is the observations $Y_i \in \mathbb{R}$, are given by

$$Y_i = r(\theta_T, X_i) + \epsilon_i \quad i = 1, \dots, n \quad (16)$$

with $r(\theta, X_i)$ the regression function known up to some **finite dimensional parameter** $\theta \in \Theta$, where Θ is a subset of \mathbb{R}^p with θ_T is the true parameter value. where $Y_i \in \mathbb{R}$, $X_i \in \mathcal{X} \subset \mathbb{R}$ are observable, $\epsilon_i \in \mathbb{R}$ is unobservable. The samples X_i , $i = 1 \dots n$ are i.i.d. with common distribution G and density function g , ϵ_i , i.i.d. $\sim f$

independent of X_i , where **the densities g and f are unknown.**

Let $p_{\theta_T}(x, y) = f(y - r(\theta_T, x))g(x)$ denote the true joint distribution of (X, Y) . Under the assumptions of the regression model (16), the ϕ -divergence between a parametric model $\{p_\theta(x, y) := f(y - r(\theta, x))g(x); \theta \in \Theta\}$ and p_{θ_T} can be written as

$$D_\phi(\theta, \theta_T) = \sup_{\alpha \in \Theta} P_{\theta_T} h(\theta, \alpha), \quad (17)$$

where θ is the escort parameter and

$$h(\theta, \alpha, x, y) := \int \phi' \left(\frac{f(y - r(\theta, x))}{f(y - r(\alpha, x))} \right) f(y - r(\theta, x))g(x) - \left[\frac{f(y - r(\theta, x))}{f(y - r(\alpha, x))} \phi' \left(\frac{f(y - r(\theta, x))}{f(y - r(\alpha, x))} \right) - \phi \left(\frac{f(y - r(\theta, x))}{f(y - r(\alpha, x))} \right) \right].$$

Note that g cancels. Furthermore, the supremum in this display is unique and it is achieved at $\alpha = \theta_T$ independently upon the value of θ . Hence, it is reasonable to estimate $D_\phi(\theta, \theta_T) := \int \phi(p_\theta/p_{\theta_T})dP_{\theta_T}$, the

ϕ -divergence between P_θ and P_{θ_T} , by

$$\widehat{D}_\phi(\theta, \theta_T) := \sup_{\alpha \in \Theta} P_n h(\theta, \alpha), \quad (18)$$

in which we have replaced P_{θ_T} by its estimate P_n , the empirical measure associated to the data.

4.1 Construction of the estimators

Use a two-step method . We split the data sample $(Y_1, X_1) \dots, (Y_n, X_n)$ into two parts

, $(Y_1, X_1) \dots, (Y_N, X_N)$

and $(Y_{N+1}, X_{N+1}), \dots, (Y_n, X_n)$, with $N \rightarrow \infty$ as $n \rightarrow \infty$ adaptive estimation (f. i. Bickel, Manski)

Initial estimate $\hat{\theta}_n$ such that $|\hat{\theta}_n - \theta_T| = O(n^{-1/2})$,
"estimate the residuals" $\tilde{\epsilon}_{iN} = Y_i - r(\hat{\theta}_n, X_i)$ $i =$

$1, \dots, N$. These residuals will be used to **construct a nonparametric density function estimator, say f_N** .

Introduce the following functions

$$m(\theta, \alpha) = \int \phi' \left(\frac{f(y - r(\theta, x))}{f(y - r(\alpha, x))} \right) f(y - r(\theta, x)) g(x) dx dy. \quad (19)$$

and

$$\begin{aligned} \varphi(\theta, \alpha, x, y) = & \frac{f(y - r(\theta, x))}{f(y - r(\alpha, x))} \phi' \left(\frac{f(y - r(\theta, x))}{f(y - r(\alpha, x))} \right) \\ & - \phi \left(\frac{f(y - r(\theta, x))}{f(y - r(\alpha, x))} \right). \end{aligned} \quad (21)$$

That is the function h defined in (??), will be written as

$$h(\theta, \alpha, x, y) = m(\theta, \alpha) - \varphi(\theta, \alpha, x, y).$$

Since the functions f and g are unknown, we will give an estimate of the function h based on the first sample of the residuals. For given θ and α , we can estimate h by

$$\hat{h}(\theta, \alpha, x, y) = \hat{m}(\theta, \alpha) - \hat{\varphi}(\theta, \alpha, x, y) \quad (22)$$

with f_N . in place of f

Now, for any θ in Θ , the divergence $D_\phi(\theta, \theta_T)$, can be estimated by

$$\widetilde{D}_\phi(\theta, \theta_T) := \sup_{\alpha \in \Theta} P_{\tilde{n}} \widehat{h}(\theta, \alpha), \quad (23)$$

where $P_{\tilde{n}}$ is the empirical distribution based on the second part of the sample $(Y_{N+1}, X_{N+1}), \dots, (Y_n, X_n)$.

In analogy with the preceding section we will define estimates of the parameter θ_T based on the estimated divergence $\widetilde{D}_\phi(\theta, \theta_T)$. It follows that

$$\tilde{\alpha}_\phi(\theta) := \arg \sup_{\alpha \in \Theta} P_{\tilde{n}} \widehat{h}(\theta, \alpha) \quad (24)$$

and

$$\tilde{\theta}_\phi := \arg \inf_{\theta \in \Theta} \sup_{\alpha \in \Theta} P_{\tilde{n}} \widehat{h}(\theta, \alpha) \quad (25)$$

5 Consistency and asymptotic distribution

(C.1) the estimate $\tilde{\alpha}_\phi(\theta)$ exists;

(C.2) for any positive δ , there exists some positive η such that for all $\alpha \in \Theta$ satisfying $\|\alpha - \theta_T\| > \delta$ we have

$$P_{\theta_T} h(\theta, \alpha) < P_{\theta_T} h(\theta, \theta_T) - \eta$$

(1) Under the assumptions (C.1), (H.0), (F.1-4), (R.1-8), (G.1-4), (K.0-2), the estimate $\widetilde{D}_\phi(\theta, \theta_T)$ converges in probability to $D_\phi(\theta, \theta_T)$.

(2) Assume that the assumptions (C.1-2), (H.0), (F.1-4), (R.1-8), (G.1-4), (K.0-2) hold then the estimate $\tilde{\alpha}_\phi(\theta)$ converges in probability to θ_T .

The conditions under which the Proposition 5 are standards. Indeed conditions (C.1)-(C.3) are those used by [?] to prove consistency of $\hat{\alpha}_\phi(\theta)$ and $\widehat{D}_\phi(\theta, \theta_T)$; Conditions (K.0)-(K.2) ensures the convergence of the kernel density estimates based on the residuals to the true disturbance density.

When all conditions (H.0-2), (F.1-6), (R.1-8), (G.1-4), (K.0-2) and (S.1) hold. Then, we have

- (a) $\sqrt{n} \left(\tilde{\alpha}_\phi(\theta) - \theta_T \right)$ converges in distribution to a centered multivariate normal random variable with covariance matrix

$$V_\phi(\theta, \theta_T) = S^{-1} M S^{-1} \quad (26)$$

If $\theta_T = \theta$, then $V_\phi(\theta, \theta_T) = I_{\theta_T}^{-1}$.

- (b) If $\theta_T = \theta$, then the statistic $\frac{2n}{\phi''(1)} \widetilde{D}_\phi(\theta, \theta_T)$ converges in distribution to a χ^2 random variable with d degrees of freedom.

- (c) If additionally assumption (S.2) holds, then when $\theta \neq \theta_T$, we have

$\sqrt{n} \left(\widetilde{D}_\phi(\theta, \theta_T) - D_\phi(\theta, \theta_T) \right)$ converges in distribution to a centered normal random variable with variance

$$\sigma_\phi^2(\theta, \theta_T) = P_{\theta_T} h(\theta, \theta_T)^2 - \left(P_{\theta_T} h(\theta, \theta_T) \right)^2. \quad (27)$$

5.0.1 Bias reduction through adaptive choice of the escort parameter

The above results prove that both estimates $\widetilde{D}_\phi(\theta, \theta_T)$ and $\widetilde{\alpha}_\phi(\theta)$ are asymptotically unbiased for all value of the escort parameter θ .

For small values of n these estimates have a significant bias.

A natural improvement of the present approach results in the plugging of an initial estimate of θ_T as an adaptive escort choice.

Let $\widehat{\theta}_{NLS}$ be the nonlinear least square estimate (NLS) of θ_T , the estimate of θ_T is easy to calculate. Therefore it converges to θ_T under the general assumptions of this paper.

By the continuity of of the derivatives of $h(\theta, \alpha)$ w.r.t α , adaptive procedure satisfies the following asymptotic result

When all conditions (H.0-2), (F.1-6), (R.1-8), (G.1-4), (K.0-2) and (S.1) hold and $\theta = \hat{\theta}_{NLS}$. Then, we have

- (a) $\sqrt{n} \left(\tilde{\alpha}_\phi(\theta) - \theta_T \right)$ converges in distribution to a centered multivariate normal random variable with covariance matrix $I_{\theta_T}^{-1}$.
- (b) The statistic $\frac{2n}{\phi''(1)} \widetilde{D}_\phi(\theta, \theta_T)$ converges in distribution to a χ^2 random variable with p degrees of freedom.