

# Bayesian Merging Of Multiple Advices And Its Application To A Cold Rolling Mill

Václav Šmíd & Pavel Ettlér

ÚTIA & Compureg

CSKI and DAR seminar, 15 January 2008

# Content

## Part I

Project Background  
Applied principles  
Variety of settings

## Part II

Merging of advices

## Part III

Software implementation

# Problem formulation

- ▶ 18 models
  - system model – static / dynamic
  - user target – maximum / moving average / estimated
  - design method – academic / industrial / simultaneous
- ▶ Data were recorded in 6 month, i.e. many different working conditions.
- ▶ The operator **did not** follow the advices.
- ▶ The designed advisers are not directly comparable (missing variances).
- ▶ We seek an external measure of quality of advising.

# Possible approaches

## 1. Strictly scientific experiment:

- ▶ test all methods under exactly the same conditions.
- ▶ impossible in production line in a factory.

## 2. Detailed modeling:

- ▶ model discrepancy between the observed data and observation that would be observed if the operator followed our recommendation.
- ▶ too much uncertainty to be modeled.

## 3. High-level black-box modeling

- ▶ we build a simple auto-regressive model of the relation between two key quantities:
  - a) closeness,  $C$ , of recommendations to true actions,
  - b) quality of operator performance,  $P$ .

## High-level model

- ▶ From a full set of 40 variables we pick two: input deviation,  $h_1$ , and output deviation,  $h_2$ .
- ▶ Large data-records are split into blocks of 1000 samples.
- ▶ Operator performance index for one block:

$$P = \frac{E(h_2^2)}{E((h_1 - \bar{h}_1)^2)},$$

$E$  denotes empirical expected value on the block of data.

- ▶ Closeness of advices:

$$C_{i,t} = E \left( 1 - \frac{\max(|u_t - u_{i,t}^*|, u_t)}{u_t} \right),$$

$u_{i,t}^*$  is the recommended action of the  $i$ th adviser, and  $u_t$  is the actual realization.

- ▶ Lets assume that  $P_t$  is related to  $C_i$  via an unknown function,  $P_t = g_i(C_i)$ .

## High-level model

- ▶ Lets assume that  $P_t$  is related to  $C_i$  via an unknown function,

$$P_t = g_i(C_i).$$

- ▶ Taylor expansion at operating point  $\bar{C}_{i,t}$  at time  $t$  yields

$$P_t = g_i(\bar{C}_{i,t}) + g_i'(\bar{C}_{i,t})(C_{i,t} - \bar{C}_{i,t}) + e_t, \quad (1)$$

where  $g_i'()$  denotes the first derivative of  $g_i()$ ,  $\bar{C}_{i,t}$  is the fixed point of expansion, and  $e_t$  is an aggregation of higher order term.

**Model:** motivated by (1)

$$P_t = b_{i,t} + a_{i,t}C_{i,t} + \sigma_{i,t}v_t, \quad (2)$$

where  $b_{i,t}, a_{i,t}, \sigma_{i,t}$  are unknown time-variant parameters.  $v_t \sim \mathcal{N}(0, 1)$  is Gaussian noise.

- ▶ time-variant parameters accommodate for time-varying expansion point, allowing fitting of the linearization to the current situation.
- ▶ Model (2) can be estimated exactly using Bayesian theory.

# Merging of advices

## Task:

Recommend an action, which if followed would lead to the highest operator's performance.

- ▶ Decision-making problem.
- ▶ Operator's performance is modeled by the high-level models.

# Merging of advices

## Task:

Recommend an action, which if followed would lead to the highest operator's performance.

- ▶ Decision-making problem.
- ▶ Operator's performance is modeled by the high-level models.

Formally:

$$u_{t+1}^{\text{mer}} = \arg \min_{u_t} E(P_{t+1} | u_{t+1}).$$

$$E(P_{t+1} | u_{t+1}) = \sum_{i=1}^{18} \alpha_{i,t} f(P_{t+1} | C_{i,t+1}(u_{t+1})),$$

$$\alpha_{i,t} = f(i_t = i | P_t, C_t) \propto f(P_t | C_{i,t}, i).$$



# Approximate merging

Evaluation of the formal problem is computationally prohibitive. We tested the following approximation:

1. winner takes all.

$$\alpha_{i,t} \approx [0, \dots, 1, \dots, 0].$$

$$\hat{i} = \arg \max f(P_t | C_{i,t}, i).$$

(Choosing just one component from the mixture).

2. Avoiding optimization of  $C_{i,t}(u_t)$ .

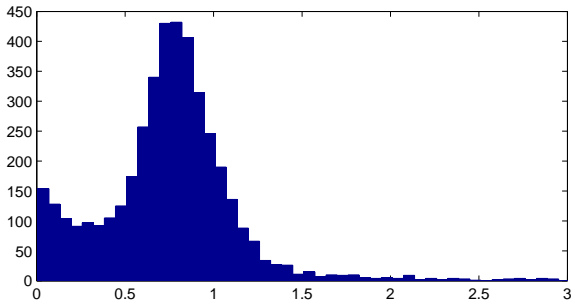
Each adviser has already designed its optimal strategy  $u_{i,t}^{(o)}$ , i.e.

$$u_{t+1}^{\text{mer}} = \arg \min_{u_t} E(P_{t+1} | u_{t+1}).$$

$$\approx u_{\hat{i}, t+1}^{(o)}.$$

## Data for the experiment

- ▶ Data set collected during 6 month of production of a cold rolling mill,
- ▶ more than 4,2 million of 10 dimensional data records,
- ▶ The set contains data from a wide range of operating condition such as different materials or different passes though the mill.
- ▶ The quality of final product was within the required range for great majority of the data, and so was the operator's performance index:

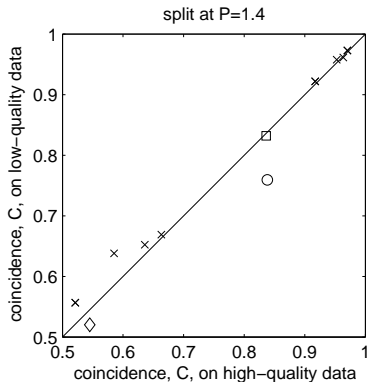
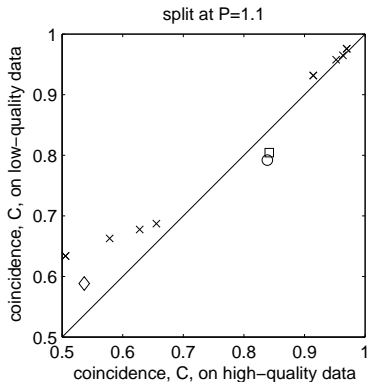


- ▶ This implies that the AGC low-level controllers worked very well, leaving only a narrow margin for improvement.

# Experimental results

- ▶ Both operator's performance index and coincidence was computed for each model for each of the 4227 data batches.
- ▶ Scatter plots of these quantities form irregular clusters, discouraging visual inspection and parametric modeling of the relation.
- ▶ Hence, we propose to choose a threshold  $\hat{P}$  of 'good' performance and split all data records in two sets:
  - ▶ high-quality data,  $P < \hat{P}$ ,
  - ▶ low-quality data,  $P \geq \hat{P}$ .
- ▶ The rationale is that good adviser should recommend actions that are:
  - ▶ close to the actual actions when the performance is good,
  - ▶ far from the actual actions when the performance is bad.

# Experimental results



- × original advisers with  $C > 0.5$ .
- the merging adviser.
- adviser  $M_I^{\text{stat}}$ ,  $M_T^{\text{mov}}$ ,  $M_A^{\text{ind}}$ .
- ◇ adviser  $M_I^{\text{dyn}}$ ,  $M_T^{\text{max}}$ ,  $M_A^{\text{simult}}$ .

## Part II Summary

- ▶ High-level black-box model was chosen as a representation of quality of advising.
- ▶ Parameters of the model were estimated using Bayesian theory.
- ▶ Merging of advices was formulated as an optimization problem under uncertainty, which was further approximated.
- ▶ The resulting algorithm is relatively robust to tuning knobs in the choice evaluation criteria.

